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Санкт-Петербургского государственного университета

Почетный работник высшего профессионального образования РФ

Опубликовано более 250 научных работ. Из них 130 включены в базу SCOPUS, 93 - в Web of Science Core Collection, более 200 включены в РИНЦ.

Индексы Хирша:

РИНЦ – 16

SCOPUS – 13

WoS – 9

Опубликовано 3 монографии и 5 учебных пособий.

Под руководством Александра А.Ю. защищено 6 кандидатских диссертаций.

Является членом редколлегии научного журнала “Nonlinear Dynamics and Systems Theory” (включен в SCOPUS)

## Гранты

1. Совместный Российско-Китайский проект "Анализ достижимости и синтез регуляторов для гибридных систем с приложениями", 2009-2010 гг. (поддержан РФФИ и ГФЕН КНР, проект № 08-08-92208-ГФЕН\_a, руководитель -- Александров А.Ю.).
2. Проект "Развитие методов исследования устойчивости и стабилизации движений нелинейных механических систем", 2013—2015 гг. (поддержан РФФИ, проект № 13-01-00376\_a, руководитель -- Александров А.Ю.).

3. Совместный Российско-Китайский проект "Моделирование, анализ устойчивости и синтез стабилизирующих управлений для гибридных автоматов на графах с приложениями в задачах управления транспортными сетями", 2015-2016 гг. (поддержан РФФИ и ГФЕН КНР, проект № 15-58-53017, руководитель -- Александров А.Ю.).
4. Проект "Развитие методов анализа устойчивости движений нелинейных динамических систем", 2016—2018 гг. (поддержан РФФИ, проект № 16-01-00587\_a, руководитель -- Александров А.Ю.).
5. Фундаментальная НИР № 9.38.674.2013 из средств Санкт-Петербургского государственного университета «Методы декомпозиции и агрегирования сложных систем с отображением их в распределенную вычислительную среду», 2013—2015 гг. (руководитель -- Александров А.Ю.).

Согласно данным  
SciVal (Elsevier),  
в Санкт-Петербургском университете  
в категории  
Aerospace Engineering,  
к которой принадлежит представленный на конкурс цикл работ, проф. А.Ю. Александров занимает **5-е** место по числу SCOPUS-публикаций за период 2013-2017 гг. (см. скриншот).

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Top 500 authors, by number of publications at St. Petersburg State University over the period 2013 to 2017. Note that some authors may no longer be affiliated with St. Petersburg State University.

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	Name	Publications ↓	Most recent publication	Citations	h-index
1.	<input type="checkbox"/> Tikhonov, Alexey A.	6	2017	44	10
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3.	<input type="checkbox"/> Kuzmin, Alexander	5	2015	16	7
4.	<input type="checkbox"/> Moskaleva, E. V.	5	2017	10	3
5.	<input type="checkbox"/> Aleksandrov, Alexander	4	2017	21	12
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8.	<input type="checkbox"/> Gavrilov, Nikolai M.	3	2015	24	12
9.	<input type="checkbox"/> Kolesnikov, Evgeny K.	3	2016	0	5
10.	<input type="checkbox"/> Kustova, Elena V.	3	2015	13	18

Представленный на конкурс цикл работ принадлежит также направлению «Автоматизация и управление». Как известно, именно по этому направлению в 2017 году СПбГУ впервые вошел в Шанхайский рейтинг и стал единственным российским университетом попавшим в топ-100 (место 51-75). При этом учитывались статьи ученых СПбГУ, число которых по данным Web of Science составило 104 (см. таблицу). На самом деле две статьи (выделены зеленым) отнесены к СПбГУ ошибочно: они относятся к ИТМО. Из 102 статей, принадлежащих СПбГУ, 11 статей написаны при участии проф. А.Ю. Александрова и 2 статьи -- при участии проф. А.А. Тихонова - соавтора представленного на конкурс цикла работ (выделены желтым). В текущем, 2018 году СПбГУ поднялся в Шанхайском рейтинге на 32-ю позицию (см. <http://www.shanghairanking.com/Shanghairanking-Subject-Rankings/automation-control.html> )

Article Title	Authors	Source	Vol.	Iss.	Pages	Year	Cited	Jou.	IF
Stability analysis for a class of systems	Aleksandrov, A. Yu.; Churilov, Alexander N.	AUTOMATICA	47	10	2286-	2011	29	5,45	
On the asymptotic stability of systems with time delay	Aleksandrov, A. Yu.; Krasovskii, N. P.	SYSTEMS & CONTROL LETTERS	61	1	127-131	2012	17	2,55	
On the Asymptotic Stability of Systems with Time Delay	Aleksandrov, A. Yu.; Pilyugin, Sergei Yu.	AUTOMATION AND CONTROL	75	5	818-821	2014	0	0,49	
Monoaxial electrodynamic systems	Aleksandrov, A. Yu.; Tikhonov, Vladimir L.	AUTOMATION AND CONTROL	74	8	1249-	2013	7	0,49	
Time-delayed feedback stabilization of systems	Aleksandrov, A. Yu.; Zhurav, Alexander I.	INTERNATIONAL JOURNAL OF CONTROL	88	10	2066-	2015	0	2,21	
Stability and Stabilization of Systems with Time Delay	Aleksandrov, A. Yu.; Korovin, Leonid M.	AUTOMATION AND CONTROL	72	6	1143-	2011	3	0,49	
Absolute stability and Lyapunov stability of systems	Aleksandrov, A. Yu.; Matrosov, Leonid S.	JOURNAL OF THE PHYSICAL MATHEMATICAL SCIENCES	351	8	4381-	2014	3	3,14	
Diagonal Lyapunov-Krasovskii stability criterion	Aleksandrov, A. Yu.; Matrosov, Leonid S.	SYSTEMS & CONTROL LETTERS	63	n/a	63-67	2014	1	2,55	
Stability Analysis for the Systems with Time Delay	Aleksandrov, A. Yu.; Zhurav, Alexander I.	AUTOMATION AND CONTROL	75	2	399-401	2014	0	0,49	
Delay-Independent Stability of Systems with Time Delay	Aleksandrov, Alexander I.	IEEE TRANSACTION ON AUTOMATIC CONTROL	59	8	2209-	2014	7	4,27	
Approximate consensus in multi-agent systems	Amelina, N. O.; Fradkov, Alexander L.	AUTOMATION AND CONTROL	73	11	1765-	2012	16	0,49	
Reconstructing the potential of a system	Avdonin, Sergei A.; Mikheyev, Alexander V.	IMA JOURNAL OF MATHEMATICS	31	1	137-141	2014	3	1,27	
Hybrid adaptive observers for systems with time delay	Bobtsov, Alexey A.; Efremov, Alexander V.	INTERNATIONAL JOURNAL OF CONTROL	25	1	33-47	2011	1	1,71	
Limiting zeros of sampled systems	Bondarko, V. A.	AUTOMATION AND CONTROL	76	8	1327-	2015	0	0,49	
Estimating passenger traffic in a system	Bure, V. M.; Mazalov, Vladimir I.	AUTOMATION AND CONTROL	76	9	1673-	2015	0	0,49	
Linear-transformation-based stabilization of systems	Chen, Yangzhou; Qu, Xi	JOURNAL OF THE PHYSICAL MATHEMATICAL SCIENCES	352	9	3447-	2015	1	3,14	
An impulse-to-impulse discrete-time system	Churilov, Alexander N.; Fradkov, Alexander L.	AUTOMATICA	50	8	2187-	2014	7	5,45	
Periodical Solutions in a System with Time Delay	Churilov, Alexander; Matrosov, Leonid S.	IEEE TRANSACTION ON AUTOMATIC CONTROL	59	3	728-731	2014	12	4,27	
A state observer for continuous-time systems	Churilov, Alexander; Matrosov, Leonid S.	AUTOMATICA	48	6	1117-	2012	7	5,45	
Necessary Stability Conditions for Systems with Time Delay	Cuvas, Carlos; Ramirez, Daniel	DELAY SYSTEMS: THEORY AND APPLICATIONS	11	n/a	3-16	2014	0	n/a	
Restoring important processes in a system	Debus, Bruno; Kirsanov, Alexander V.	CHEMOMETRICS AND QUALITY ENGINEERING	146	n/a	241-245	2015	0	2,30	
NONSMOOTH PROBLEMS OF CONTROL	Dolgopoli, Maxim	ESAIM-CONTROL OPTIMIZATION AND CALCULUS OF VARIATIONS	20	4	1153-	2014	0	1,54	
Matrix Formalism of Degen-Dudarenko, N. A.; Ushakov, Vladimir I.		JOURNAL OF AUTOCONTROL	43	6	30-39	2011	0	n/a	
Synchronization in Networked Systems	Dzhunusov, I. A.; Fradkov, Alexander L.	AUTOMATION AND CONTROL	72	8	1615-	2011	9	0,49	
Natural wave control in a system	Efimov, Denis V.; Fradkov, Alexander L.	SYSTEMS & CONTROL LETTERS	61	9	887-891	2012	1	2,55	
Design of impulsive adaptive control systems	Efimov, Denis; Fradkov, Alexander L.	INTERNATIONAL JOURNAL OF CONTROL	29	6	765-771	2015	3	1,71	
Exciting multi-DOF systems	Efimov, Denis; Fradkov, Alexander L.	AUTOMATICA	49	6	1782-	2013	4	5,45	
Necessary conditions for the stability of systems	Egorov, A. V.; Mondie, Jean-Christophe	INTERNATIONAL JOURNAL OF CONTROL	24	12	1760-	2014	4	3,39	
Necessary stability conditions for systems with time delay	Egorov, Alexey V.; Morozov, Alexander V.	AUTOMATICA	50	12	3204-	2014	6	5,45	
Designs of optimal switching control systems	Feoktistova, V.; Matrosov, Leonid S.	MATHEMATICS OF MECHANICS AND SOLID STRUCTURES	24	4	477-501	2012	4	1,67	
Decentralized adaptive control of systems	Fradkov, A. L.; Grigoriev, Alexander L.	AUTOMATION AND CONTROL	74	5	829-831	2013	2	0,49	
Decentralized adaptive control of systems	Fradkov, A. L.; Junussov, Alexander L.	INTERNATIONAL JOURNAL OF CONTROL	27	9	729-731	2013	6	1,71	
Passification based synchronization of systems	Fradkov, Alexander L.; Matrosov, Leonid S.	AUTOMATICA	55	n/a	287-291	2015	2	5,45	
Compensation of disturbances in a system	Furtat, Igor B.; Fradkov, Alexander L.	AUTOMATICA	60	n/a	239-243	2015	1	5,45	
Invariant Stabilization of a System	Gelig, A. H.; Zuber, I. E.	AUTOMATION AND CONTROL	72	9	1941-	2011	3	0,49	
Using the direct and indirect methods for stabilization	Gelig, A. Kh.; Zuber, I. E.	AUTOMATION AND CONTROL	73	9	1498-	2012	1	0,49	
Using the direct and indirect methods for stabilization	Gelig, A. Kh.; Zuber, I. E.	AUTOMATION AND CONTROL	73	8	1337-	2012	2	0,49	
The nonasymptotic confidence interval for the estimate	Granichin, O. N.	AUTOMATION AND CONTROL	73	1	20-30	2012	7	0,49	
Stochastic approximation algorithms	Granichin, O. N.	AUTOMATION AND CONTROL	76	5	762-771	2015	3	0,49	
A randomized algorithm for the stabilization of systems	Granichin, O. N.; Shalynov, Alexander V.	AUTOMATION AND CONTROL	72	4	754-761	2011	0	0,49	
Simultaneous Perturbation Stochastic Approximation	Granichin, Oleg; Amelina, N. O.	IEEE TRANSACTION ON AUTOMATIC CONTROL	60	6	1653-	2015	8	4,27	
Stability of composite systems	Gromov, Dmitry; Caines, Bruce W.	IET CONTROL THEORY AND APPLICATIONS	9	11	1629-	2015	0	2,54	
Kalman-Popov-Yakubovich conditions for the stability of systems	Gusev, S. V.	AUTOMATION AND CONTROL	75	1	18-33	2014	0	0,49	
Collision-free navigation of a system	Hoy, Michael; Matveev, Alexey S.	ROBOTICA	30	n/a	537-541	2012	4	1,55	
Algorithms for collision-free navigation of a system	Hoy, Michael; Matveev, Alexey S.	ROBOTICA	33	3	463-467	2015	10	1,55	
Collision free cooperative control of systems	Hoy, Michael; Matveev, Alexey S.	ROBOTICS AND AUTOMATION	60	10	1253-	2012	8	1,95	
An extension of the prediction method for systems	Kharitonov, Vladimir L.	AUTOMATICA	50	1	211-215	2014	13	5,45	
Predictor based stabilization of systems	Kharitonov, Vladimir L.	AUTOMATICA	52	n/a	125-131	2015	5	5,45	
On the uniqueness of Lyapunov functionals	Kharitonov, Vladimir L.	SYSTEMS & CONTROL LETTERS	61	3	397-401	2012	4	2,55	

Lyapunov Functionals and Stability of Systems	Kharitonov, Vladimir L.	TIME DELAY SYSTEMS	423	n/a	3-17	2012	0	n/a	
Coulomb Control of Polygonal Systems	Khimshashvili, G.; Panjavi, Amir	JOURNAL OF DYNAMIC SYSTEMS, MEASUREMENTS AND CONTROL	20	4	491-501	2014	2	0,71	
On one method of solving the problem of stabilization	Kvitko, A. N.	AUTOMATION AND CONTROL	73	12	2021-	2012	1	0,49	
Solving the global boundary value problem	Kvitko, A. N.	AUTOMATION AND CONTROL	76	1	44-63	2015	0	0,49	
Stable Walking Gaits for a T La Hera, Pedro X. Miral		IEEE TRANSACTION ON ROBOTICS	29	3	589-601	2013	8	4,04	
Pyragas stabilizability via delay feedback	Leonov, G. A.	SYSTEMS & CONTROL LETTERS	69	n/a	34-37	2014	2	2,55	
A Numerical Method for the Stabilization of Systems	Letyagina, Olga N.; Zharov, Alexander V.	TIME DELAY SYSTEMS	423	n/a	265-271	2012	1	n/a	
About the necessity of Popov's criterion for the stability of systems	Lipkovich, M. M.; Fradkov, Alexander L.	AUTOMATION AND CONTROL	76	5	801-805	2015	0	0,49	
Non-constant discounting in the stability of systems	Marin-Solano, Jesus; Sotomayor, Juan	AUTOMATICA	47	12	2626-	2011	8	5,45	
A method for reactive navigation of a system	Matveev, A. S.; Hoy, Michael	AUTOMATICA	49	5	1268-	2013	6	5,45	
3D environmental extremum seeking control	Matveev, Alexey S.; Ho, Myung H.	AUTOMATICA	50	7	1802-	2014	4	5,45	
The problem of boundary value control of a system	Matveev, Alexey S.; Ho, Myung H.	ROBOTICS AND AUTOMATION	61	3	312-315	2013	4	1,95	
A globally converging algorithm for the stabilization of systems	Matveev, Alexey S.; Ho, Myung H.	AUTOMATICA	54	n/a	292-301	2015	3	5,45	
Robot navigation for monitoring a system	Matveev, Alexey S.; Ho, Myung H.	AUTOMATICA	62	n/a	227-231	2015	0	5,45	
Nonlinear sliding mode control of a system	Matveev, Alexey S.; Ho, Myung H.	ROBOTICS AND AUTOMATION	61	9	973-981	2013	10	1,95	
A method for guidance and control of a system	Matveev, Alexey S.; Teplukhin, Alexander V.	AUTOMATICA	47	3	515-519	2011	36	5,45	
Navigation of a unicycle-like system	Matveev, Alexey S.; Teplukhin, Alexander V.	AUTOMATICA	47	1	85-91	2011	33	5,45	
Range-only measurements for the stabilization of systems	Matveev, Alexey S.; Teplukhin, Alexander V.	AUTOMATICA	47	1	177-181	2011	29	5,45	
Method for tracking of environment parameters	Matveev, Alexey S.; Teplukhin, Alexander V.	AUTOMATICA	48	9	2252-	2012	12	5,45	
Real-time navigation of a mobile robot	Matveev, Alexey S.; Wertz, Johannes	ROBOTICS AND AUTOMATION	60	6	769-771	2012	31	1,95	
Synthesis of Razumikhin and Melnikov's stability criterion	Mel'nik, A. V.	AUTOMATION AND CONTROL	76	5	909-911	2015	0	0,49	
Critical frequencies and stability of systems	Mejro, Gilberto; Kharitonov, Vladimir L.	SYSTEMS & CONTROL LETTERS	62	9	781-783	2013	5	2,55	
Computation of Imaginary Parts of Eigenvalues	Ochoa, Gilberto; Mondrago, Juan	TIME DELAY SYSTEMS	423	n/a	61-72	2012	0	n/a	
Method of Optimization in Control Systems	Ostov, Yu Ya; Ivanov, Alexander V.	AUTOMATION AND CONTROL	75	2	294-301	2014	0	0,49	
Cooperative surveillance of a system	Ovchinnikov, K.; Semak, Alexander V.	ROBOTICS AND AUTOMATION	72	n/a	164-171	2015	0	1,95	
Stable cooperation in stochastic systems	Parilina, E. M.	AUTOMATION AND CONTROL	76	6	1111-	2015	0	0,49	
Node-consistent core for a system	Parilina, Elena; Zaccour, Yacine	AUTOMATICA	53	n/a	304-313	2015	3	5,45	
Adaptive crawler for external disturbance rejection	Pechnikov, A. A.; Chervinskiy, Alexander V.	AUTOMATION AND CONTROL	75	3	587-591	2014	0	0,49	
Formation of new coalition in a system	Petrosian, O. L.	AUTOMATION AND CONTROL	76	11	2070-	2015	0	0,49	
Conditions for sustainable development of a system	Petrosjan, L. A.; Zenkevich, Alexander V.	AUTOMATION AND CONTROL	76	10	1894-	2015	0	0,49	
Multistage network games	Petrosyan, L. A.; Sedukhin, Alexander V.	AUTOMATION AND CONTROL	75	8	1532-	2014	0	0,49	
Lower Semicontinuity of the Value Function	Pilyugin, Sergei Yu.	JOURNAL OF DYNAMIC SYSTEMS, MEASUREMENTS AND CONTROL	21	4	559-561	2015	0	0,71	
A non-quadratic criterion for the stability of systems	Pogromsky, A. Y.; Matrosov, Leonid S.	SYSTEMS & CONTROL LETTERS	62	5	408-411	2013	5	2,55	
Frequency-domain criteria for the stability of systems	Proskurnikov, A. V.	AUTOMATION AND CONTROL	75	11	1982-	2014	5	0,49	
Consensus in nonlinear systems	Proskurnikov, A. V.	AUTOMATION AND CONTROL	76	9	1551-	2015	2	0,49	
Consensus in switching networks	Proskurnikov, Anton V.	AUTOMATICA	49	2	488-491	2013	16	5,45	
Average consensus in networks	Proskurnikov, Anton V.	AUTOMATICA	49	9	2928-	2013	15	5,45	
NONLINEAR CONSENSUS ALGORITHMS	Proskurnikov, Anton V.	ASIAN JOURNAL OF CONTROL	16	5	1277-	2014	5	1,42	
Time-consistent Shapley value	Reddy, Puduru V.; Shevchuk, Alexander V.	AUTOMATICA	49	6	1521-	2013	3	5,45	
Linear matrix inequality-based stabilization of systems	Seifullaev, R. E.; Fradkov, Alexander L.	AUTOMATION AND CONTROL	76	6	989-1001	2015	0	0,49	
Passification-based decentralized control of systems	Selivanov, Anton; Fradkov, Alexander L.	JOURNAL OF THE PHYSICAL MATHEMATICAL SCIENCES	352	1	52-72	2015	7	3,14	
Passification-based adaptive control of systems	Selivanov, Anton; Fridman, E.	AUTOMATICA	54	n/a	107-111	2015	2	5,45	
The Hamilton-Jacobi-Bellman equation for a system	Shevkopyas, E. V.	AUTOMATION AND CONTROL	75	5	959-961	2014	0	0,49	
An Example of a Vector Field	Tikhomirov, Sergey	JOURNAL OF DYNAMIC SYSTEMS, MEASUREMENTS AND CONTROL	21	4	643-646	2015	0	0,71	
Optimizing the Electrodynamic System	Tikhonov, A. A.; Spasic, Miroslav	AUTOMATION AND CONTROL	72	9	1898-	2011	8	0,49	
Synchronization of nonlinear systems	Usik, E. V.	AUTOMATION AND CONTROL	73	8	1305-	2012	3	0,49	
Degenerate problems of the stabilization of systems	Veremey, E. I.; Eremin, Alexander V.	AUTOMATION AND CONTROL	76	6	1094-	2015	0	0,49	
Computation of algebraic Riccati equations	Yakhontov, S. V.	AUTOMATION AND CONTROL	73	2	408-411	2012	0	0,49	
Subgame consistent cooperation in a system	Yeung, David W. K.; Petráš, Petr	AUTOMATICA	59	n/a	84-89	2015	1	5,45	